

Scalable Localization with Mobility Prediction for UWSN

Participants: Zhong Zhou, Jun-Hong Cui and Amvrossios Bagtzoglou

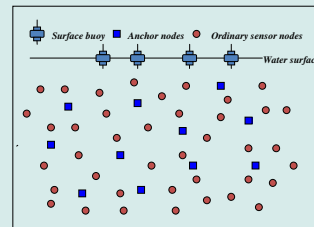
Problem:

- Challenges in UWSN: acoustic communication, node mobility, 3-D networks, and large scale
- Utilizing mobility: underwater objects move with temporal correlation and spatial correlation
- Our objective: design a scalable localization scheme with low overhead while good performance

Proposed Solution: Scalable Localization with Mobility Prediction (SLMP)

Network Model: hierarchical network architecture

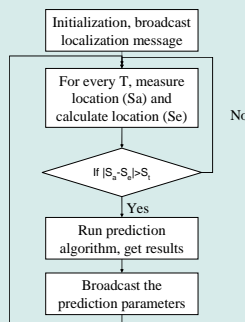
- Surface buoy: can be localized by GPS or other means
- Anchor node: communicate with buoys to get localized
- Ordinary node: can only communicate with its neighbors



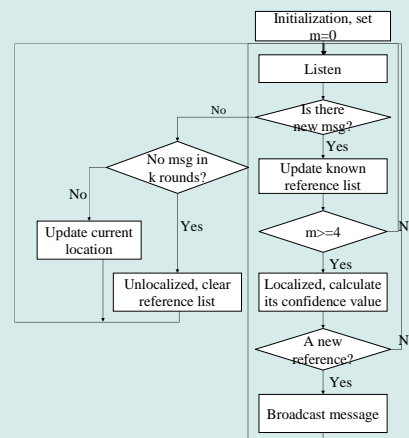
The Main Idea:

- Anchor nodes do mobility prediction based on the temporal correlation, and broadcast their model parameters
- Ordinary node do mobility prediction based on the spatial correlation and the received messages.

◆ Anchor node mobility prediction



◆ Ordinary node mobility prediction



Performance Evaluation:

